NSF 00-6



Upgrading, Development and Integration of Next Generation Earthquake Engineering Experimental Capability at Rensselaer's 100 g-ton Geotechnical Centrifuge



Submitted by: Ricardo Dobry Tarek Abdoun Ahmed Elgamal Mourad Zeghal Thomas Zimmie

RPI NEES SITE



 2D Shaker & 2D Laminar Box • 4-D In-flight Robot • Web-Based Data Acquisition Advanced Sensing Other Aspects – Data Management - Tele-observation & Tele-operation Visualization & System Identification

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• 2D Shaker & 2D Laminar Box



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2D Shaker & 2D Laminar Box 4-D In-flight Robot









Data Management



 Individual test data recorded in Data Base with relevant test information

• Timely release of Data Base after review

 NEES Electronic Journal: articles of interpreted series of centrifuge tests with complete Data Base (peer review of both article and Data Base)

Tele-observation



 Interactive teleconferencing Install web & video cameras in centrifuge & model preparation rooms Monitor measured data in real time Pilot project with UCSD Visualization of measured data System Identification techniques to evaluate model response

Tele-operation



 Secure & reliable connection Limited by safety concerns Feasible applications: - in-flight robot operation sending shaker triggering signal Broader definition of tele-operation

Advanced Sensing



 High speed cameras Advanced sensors - Wireless sensors - MEMS sensors - Buried targets - Fiber-optic sensors



